

## Technical data

### Electrical properties

Operating voltage: 8 ... 32 V DC

Current consumption: 150 mA @ 12V

### Mechanical properties

Weight: 0.2 kg

Ingress protection: IP 67

Fitting: 4 x M4

### Ambient conditions

Operating temperature range: -40 ... +85 °C

Storage temperature range: -40 ... +85 °C

### General Features

Inputs: 2x 6 (12) Digital high side / Analog inputs

Outputs: 2x 6 (12) Digital/PWM open loop outputs (2A max)  
2x 1 (2) Digital/PWM open loop outputs (5A max)

Connector: 36 pin JST 36ZRO-B-1A

### Interfaces

CAN: 2x CAN BUS (11/29 bit identifier), ISO 11898-2

### Electronic features

Microprocessor: 2x ARM® Cortex®-M4 series, 32bit core (App)  
1x ARM® Cortex®-M3 series, 32bit core (WDO)

Clock rate: 168 MHz

FLASH memory size: 2 MB (for each microprocessor)

RAM memory size: 256 KB / 4 KB backup (for each microprocessor)

Datalogger memory size: 256 KB (shared)

Other: Real Time Clock  
WDO circuit with internal relays

### Standards

EMC: EN 61000-6-2:2005  
EN 61000-6-4:2007 + A1:2011

Vibration, Shock and Free Fall: EN 60068-2-6:2007 / EN 60068-2-27:2009

Temperature: EN60068-2-1, N14Nb, -2, -78, -30

### Failure Rate, DC and CCF

Internal architecture: Cat 3 as 13849-1

Analysis method: Parts count method (assuming 50% dangerous failure)

Data collection: MIL-HDBK-217F-Notice 2 and manufacturer information

Conditions: Normal operating condition (40°, mobile application)

Operating time: Round the clock

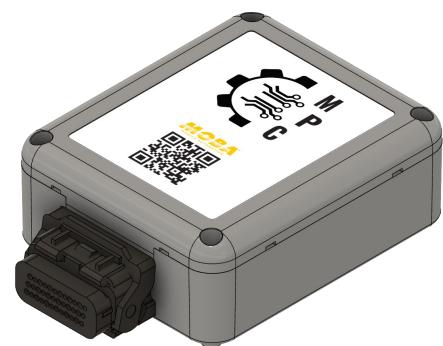
Note: MTTFd related to one of the two redundant channels

$\lambda_d$ : 21930 FIT/10<sup>10</sup> hrs

MTTFd: 104 years

DC: 60%

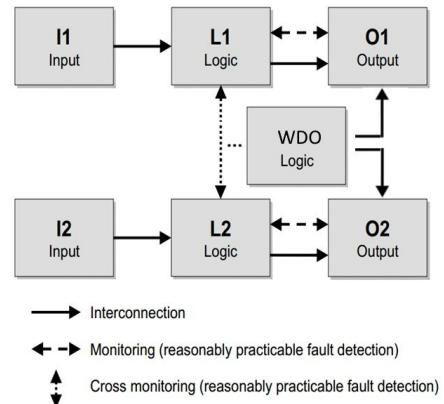
CCF: Requirements achieved



### Features:

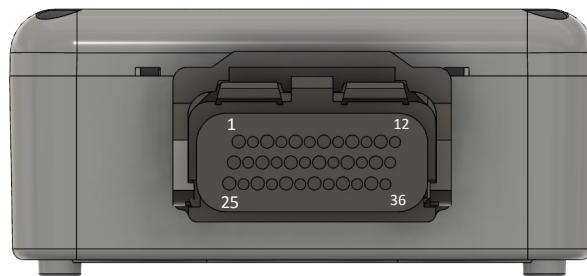
- » Inversion of polarity protection.
- » Over voltage protection.
- » Load Dump Protection.

### Architecture block diagram:



Field for notes:

## Connections



Connector		
<b>1</b>	DO1_B - PWM1_B	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>2</b>	DO2_B - PWM2_B	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>3</b>	DO3_B - PWM3_B	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>4</b>	DO4_B - PWM4_B	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>5</b>	DO5_B - PWM5_B	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>6</b>	DO6_B	Digital high side Output 5A (with ON-OFF status feedback)
<b>7</b>	DO0_A - PWM0_A	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>8</b>	DO1_A - PWM1_A	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>9</b>	DO2_A - PWM2_A	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>10</b>	DO3_A - PWM3_A	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>11</b>	DO4_A - PWM4_A	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>12</b>	DO5_A - PWM5_A	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>13</b>	DO0_B - PWM0_B	Digital/PWM high side Output 2A, closed loop (with ON-OFF status feedback)
<b>14</b>	DI0_B - ADC0_B	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc, Frequency
<b>15</b>	CAN-H 1	CAN-bus 1 high (A-B)
<b>16</b>	CAN-L 1	CAN-bus 1 low (A-B)
<b>17</b>	CAN-H 2	CAN-bus 2 high (A-B)
<b>18</b>	CAN-L 2	CAN-bus 2 low (A-B)
<b>19</b>	DI0_A - ADC0_A	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc, Frequency
<b>20</b>	DI1_A - ADC1_A	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc, Frequency
<b>21</b>	DI2_A - ADC2_A	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>22</b>	DI3_A - ADC3_A	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>23</b>	DI4_A - ADC4_A	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>24</b>	DI5_A - ADC5_A	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>25</b>	+ Operating voltage	+ Power supply
<b>26</b>	- Operating voltage	- Power supply
<b>27</b>	DI1_B - ADC1_B	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc, Frequency
<b>28</b>	DI2_B - ADC2_B	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>29</b>	DI3_B - ADC3_B	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>30</b>	DI4_B - ADC4_B	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>31</b>	DI5_B - ADC5_B	Digital/Analog high side input 0-25 mA, 0-5 Vdc, 0-32 Vdc
<b>32</b>	+VP0_A	+ Power supply for outputs (DO0_A - DO3_A)
<b>33</b>	+VP1_A	+ Power supply for outputs (DO4_A - DO6_A)
<b>34</b>	+VP0_B	+ Power supply for outputs (DO0_B - DO3_B)
<b>35</b>	+VP1_B	+ Power supply for outputs (DO4_B - DO6_B)
<b>36</b>	DO6_A	Digital high side Output 5A (with ON-OFF status feedback)

**Dimensions (mm)**

